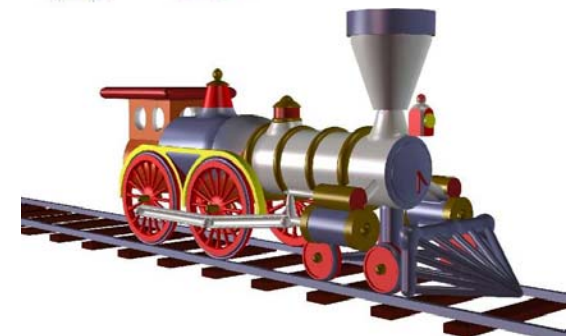
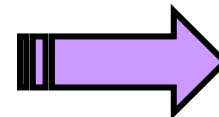
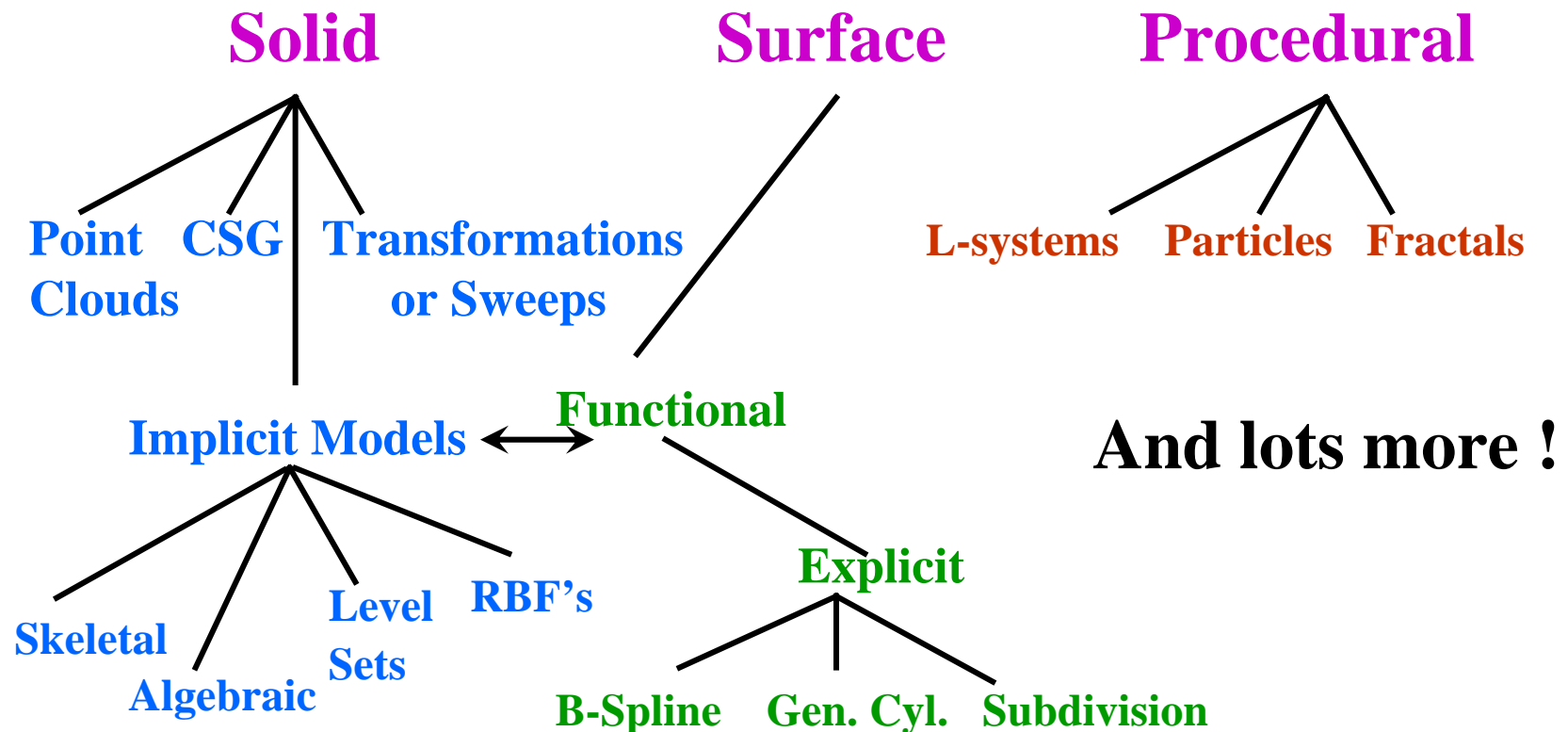


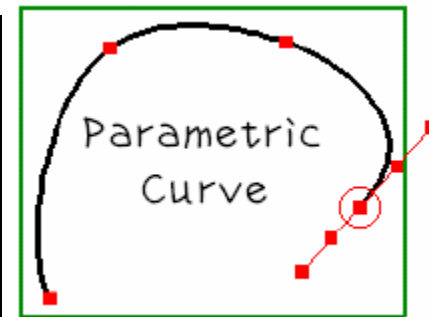
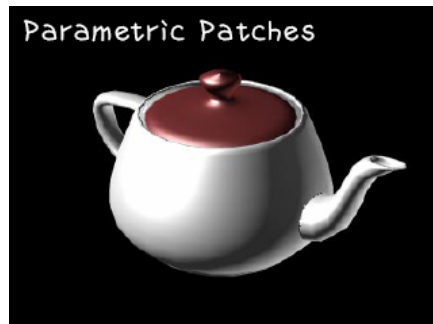
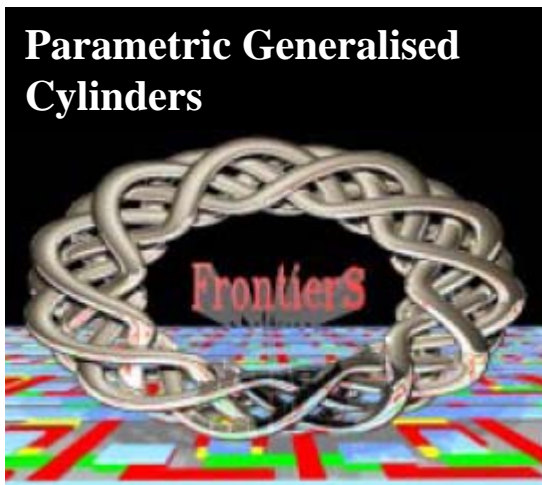
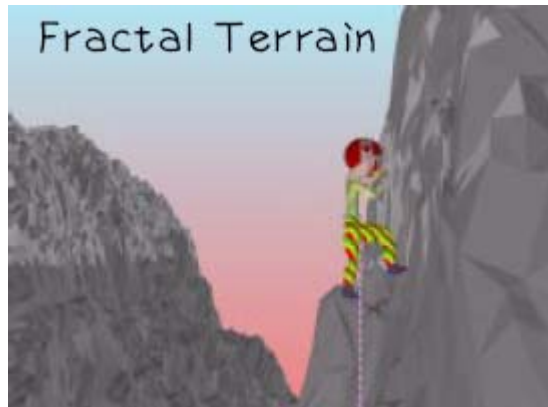
CSC 405
Modelling Overview
by Brian Wyvill

The University of Victoria
Graphics Group



Modelling Methods for Computer Graphics

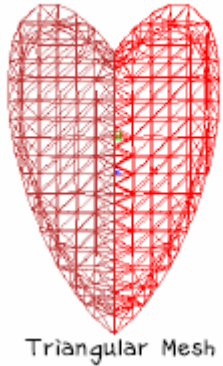




Implicit Model

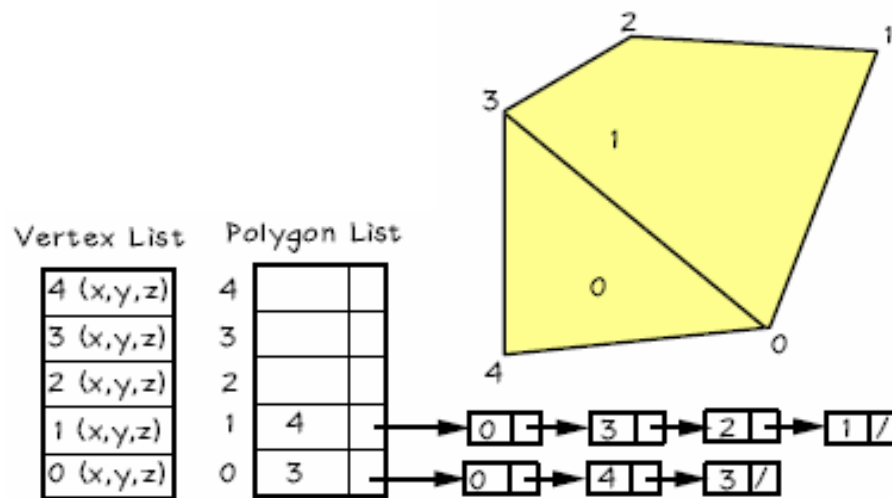


Polygon Meshes



Mesh Consistency

All polygons closed, all edges used once but less than n-times. Each vertex is referenced by at least two edges (closed mesh). Some applications require planarity, no holes etc.



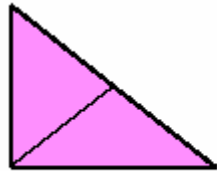
Edge List

5	0	3	1	0
4	1	0	1	/
3	2	1	1	/
2	3	2	1	/
1	4	3	0	/
0	0	4	0	/

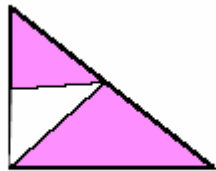
vtx 1 vtx 2 poly1 poly2



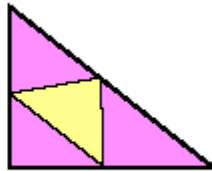
Subdividing Triangles



One edge



Two edge



Three edge

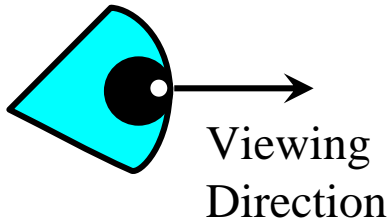


Sliver triangle

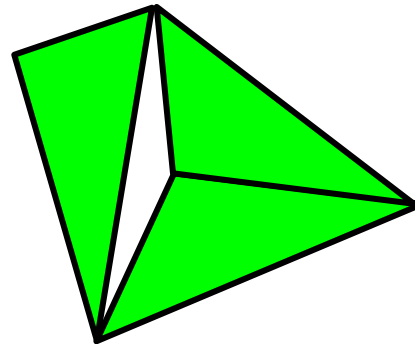
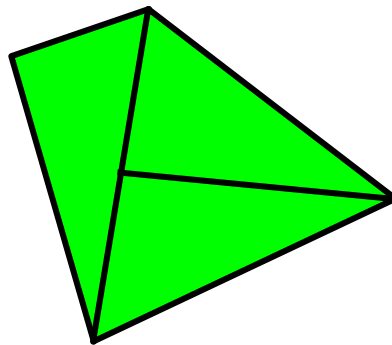


Degenerate

subdivide triangle cracks or T-intersection Problem



Viewing
Direction

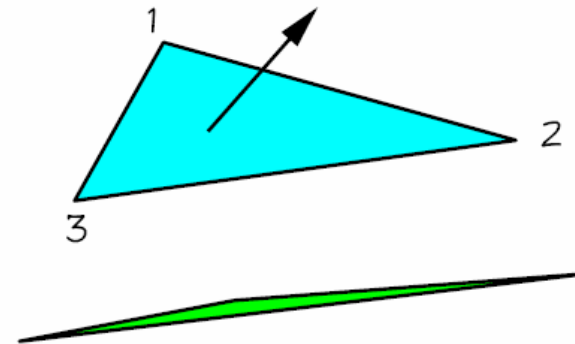
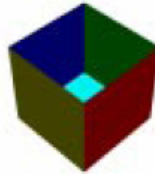


Hole in the mesh

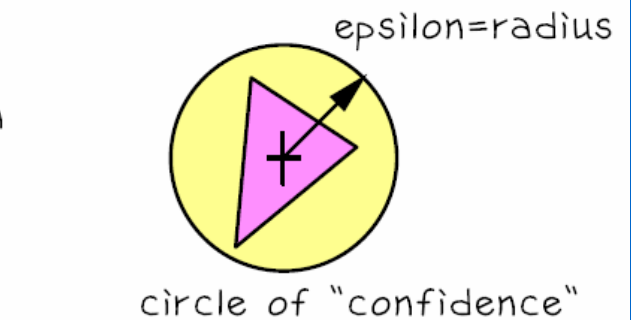


Using Triangle Meshes

1. Make sure triangles defined in a consistent direction, e.g. counter-clockwise indicates outwards normal.



2. Check for co-linear vertices or all vertices within epsilon of each other.

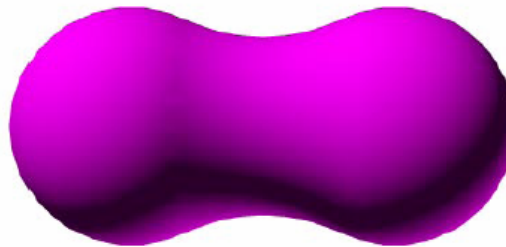


3. Rendering speed (few triangles) Vs. Smooth curved surfaces.

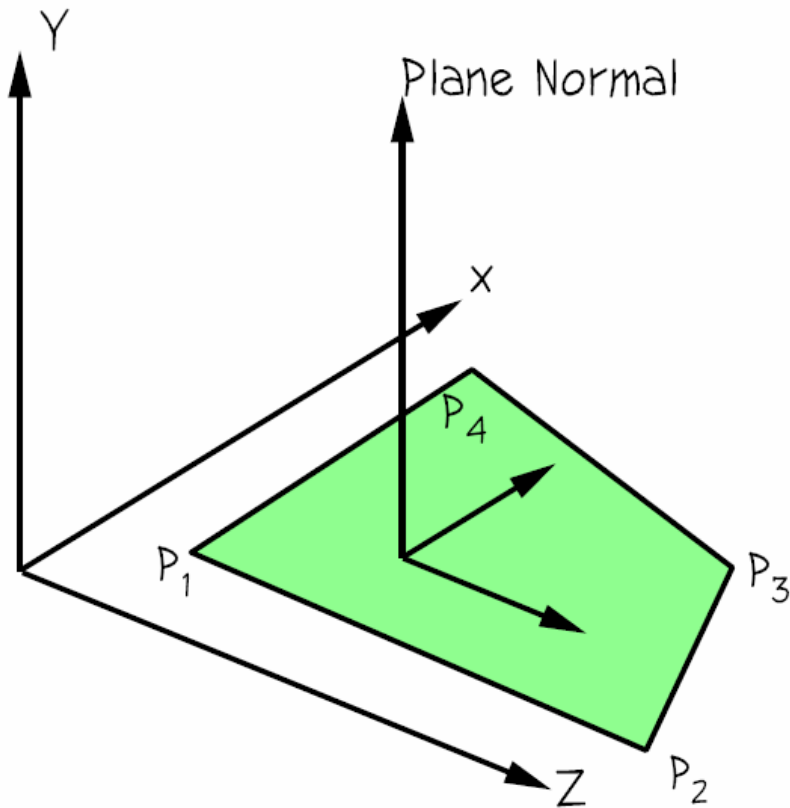
3016 polygons

408 polygons

4. Silhouette Edges.



Plane Equation and Normal



$A=C=0$ for this plane

$$Ax + By + Cz + D = 0$$

A, B, C, D can be computed from 3 non-colinear points, 4th equation is the plane equation. (Write it as determinants and expand by cofactors).

Normal to the plane is given by coefficients $[A \ B \ C]$

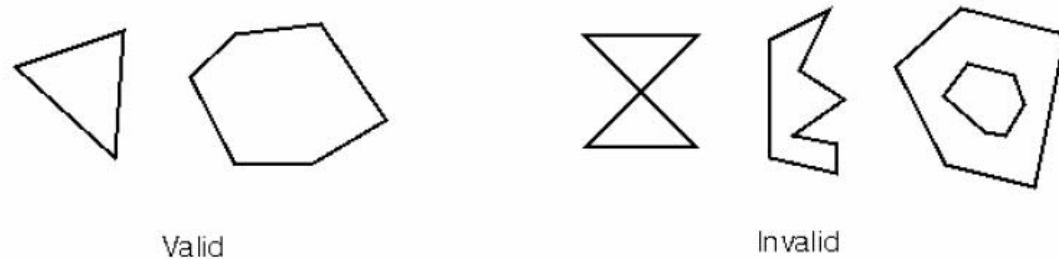
Can also compute normal as cross product of 2 edges:

$$P_1P_2 \times P_1P_4$$

Zero cross product indicates colinear vertices.



OpenGL Polygons and Triangle Meshes



OpenGL allows convex polygons to be specified:

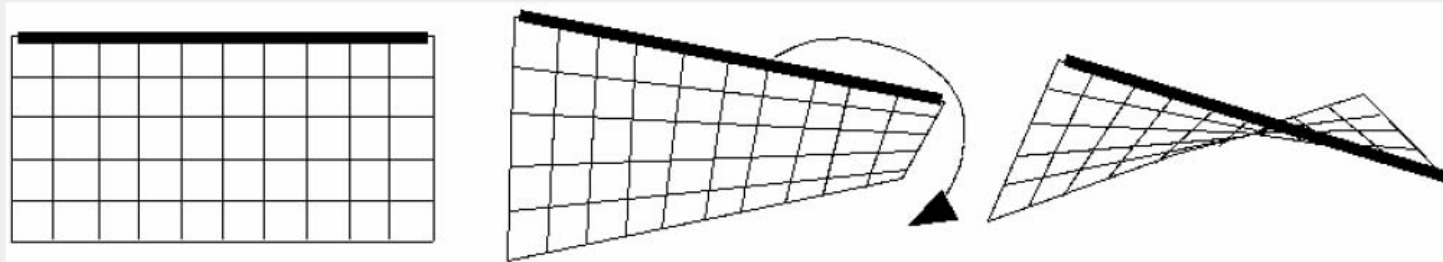


Figure 2-3 Nonplanar Polygon Transformed to Nonsimple Polygon

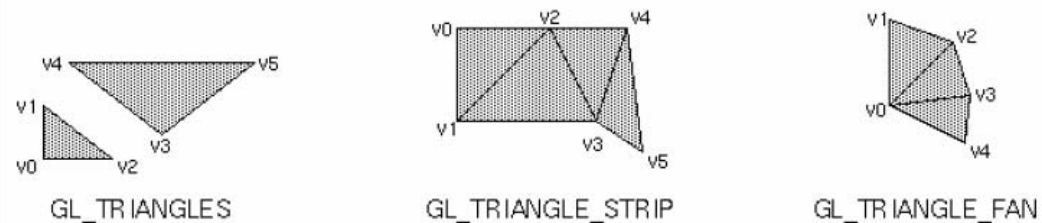


Figure 2-6 Geometric Primitive Types

